

NAG C Library Function Document

nag_pde_parab_1d_euler_exact (d03pxc)

1 Purpose

nag_pde_parab_1d_euler_exact (d03pxc) calculates a numerical flux function using an Exact Riemann Solver for the Euler equations in conservative form. It is designed primarily for use with the upwind discretisation schemes nag_pde_parab_1d_cd (d03pfc), nag_pde_parab_1d_cd_ode (d03plc) or nag_pde_parab_1d_cd_ode_remesh (d03psc), but may also be applicable to other conservative upwind schemes requiring numerical flux functions.

2 Specification

```
void nag_pde_parab_1d_euler_exact (const double uleft[], const double uright[],
    double gamma, double tol, Integer niter, double flux[], Nag_D03_Save *saved,
    NagError *fail)
```

3 Description

nag_pde_parab_1d_euler_exact (d03pxc) calculates a numerical flux function at a single spatial point using an Exact Riemann Solver (see Toro (1996) and Toro (1989)) for the Euler equations (for a perfect gas) in conservative form. The user must supply the *left* and *right* solution values at the point where the numerical flux is required, i.e., the initial left and right states of the Riemann problem defined below. In nag_pde_parab_1d_cd (d03pfc), nag_pde_parab_1d_cd_ode (d03plc) and nag_pde_parab_1d_cd_ode_remesh (d03psc), the left and right solution values are derived automatically from the solution values at adjacent spatial points and supplied to the function argument **numflx** from which the user may call nag_pde_parab_1d_euler_exact (d03pxc).

The Euler equations for a perfect gas in conservative form are:

$$\frac{\partial U}{\partial t} + \frac{\partial F}{\partial x} = 0, \quad (1)$$

with

$$U = \begin{bmatrix} \rho \\ m \\ e \end{bmatrix} \quad \text{and} \quad F = \begin{bmatrix} \frac{m^2}{\rho} + (\gamma - 1) \left[e - \frac{m^2}{2\rho} \right] \\ \frac{me}{\rho} + \frac{m}{\rho} (\gamma - 1) \left[e - \frac{m^2}{2\rho} \right] \end{bmatrix}, \quad (2)$$

where ρ is the density, m is the momentum, e is the specific total energy and γ is the (constant) ratio of specific heats. The pressure p is given by

$$p = (\gamma - 1) \left(e - \frac{\rho u^2}{2} \right), \quad (3)$$

where $u = m/\rho$ is the velocity.

The function calculates the numerical flux function $F(U_L, U_R) = F(U^*(U_L, U_R))$, where $U = U_L$ and $U = U_R$ are the left and right solution values, and $U^*(U_L, U_R)$ is the intermediate state $\omega(0)$ arising from the similarity solution $U(y, t) = \omega(y/t)$ of the Riemann problem defined by

$$\frac{\partial U}{\partial t} + \frac{\partial F}{\partial y} = 0, \quad (4)$$

with U and F as in (2), and initial piecewise constant values $U = U_L$ for $y < 0$ and $U = U_R$ for $y > 0$. The spatial domain is $-\infty < y < \infty$, where $y = 0$ is the point at which the numerical flux is required.

The algorithm is termed an Exact Riemann Solver although it does in fact calculate an approximate solution to a true Riemann problem, as opposed to an Approximate Riemann Solver which involves some form of alternative modelling of the Riemann problem. The approximation part of the Exact Riemann

Solver is a Newton–Raphson iterative procedure to calculate the pressure, and the user must supply a tolerance **tol** and a maximum number of iterations **niter**. Default values for these parameters can be chosen.

A solution can not be found by this function if there is a vacuum state in the Riemann problem (loosely characterised by zero density), or if such a state is generated by the interaction of two non-vacuum data states. In this case a Riemann solver which can handle vacuum states has to be used (see Toro (1996)).

4 References

Toro E F (1996) *Riemann Solvers and Upwind Methods for Fluid Dynamics* Springer–Verlag

Toro E F (1989) A weighted average flux method for hyperbolic conservation laws *Proc. Roy. Soc. Lond.* **A423** 401–418

5 Parameters

- 1: **uleft**[3] – const double *Input*
On entry: **uleft**[$i - 1$] must contain the left value of the component U_i for $i = 1, 2, 3$. That is, **uleft**[0] must contain the left value of ρ , **uleft**[1] must contain the left value of m and **uleft**[2] must contain the left value of e .
- 2: **uright**[3] – const double *Input*
On entry: **uright**[$i - 1$] must contain the right value of the component U_i for $i = 1, 2, 3$. That is, **uright**[0] must contain the right value of ρ , **uright**[1] must contain the right value of m and **uright**[2] must contain the right value of e .
- 3: **gamma** – double *Input*
On entry: the ratio of specific heats γ .
Constraint: **gamma** > 0.0.
- 4: **tol** – double *Input*
On entry: the tolerance to be used in the Newton-Raphson procedure to calculate the pressure. If **tol** is set to zero then the default value of 1.0×10^{-6} is used.
Constraint: **tol** \geq 0.0.
- 5: **niter** – Integer *Input*
On entry: the maximum number of Newton-Raphson iterations allowed. If **niter** is set to zero then the default value of 20 is used.
Constraint: **niter** \geq 0.
- 6: **flux**[3] – double *Output*
On exit: **flux**[$i - 1$] contains the numerical flux component \hat{F}_i for $i = 1, 2, 3$.
- 7: **saved** – Nag_D03_Save * *Input/Output*
Note: **saved** is a NAG defined structure. See Section 2.2.1.1 of the Essential Introduction.
On entry: data concerning the computation required by nag_pde_parab_1d_euler_exact (d03pxc) and passed through to **numflx** from one of the integrator functions nag_pde_parab_1d_cd (d03pfc), nag_pde_parab_1d_cd_ode (d03plc), or nag_pde_parab_1d_cd_ode_remesh (d03psc).
On exit: modified data required by the integrator function.

8: **fail** – NagError *

Input/Output

The NAG error parameter (see the Essential Introduction).

6 Error Indicators and Warnings

NE_INT

On entry, **niter** = $\langle value \rangle$.

Constraint: **niter** ≥ 0 .

NE_ITER_FAIL_CONV

Newton-Raphson iteration failed to converge.

NE_REAL

Right pressure value $pr < 0.0$: $pr = \langle value \rangle$.

Left pressure value $pl < 0.0$: $pl = \langle value \rangle$.

On entry, **uright**[0] < 0.0 : **uright**[0] = $\langle value \rangle$.

On entry, **uleft**[0] < 0.0 : **uleft**[0] = $\langle value \rangle$.

On entry, **tol** = $\langle value \rangle$.

Constraint: **tol** ≥ 0.0 .

On entry, **gamma** = $\langle value \rangle$.

Constraint: **gamma** > 0.0 .

NE_VACUUM

A vacuum condition has been detected.

NE_ALLOC_FAIL

Memory allocation failed.

NE_BAD_PARAM

On entry, parameter $\langle value \rangle$ had an illegal value.

NE_INTERNAL_ERROR

An internal error has occurred in this function. Check the function call and any array sizes. If the call is correct then please consult NAG for assistance.

7 Accuracy

The algorithm is exact apart from the calculation of the pressure which uses a Newton-Raphson iterative procedure, the accuracy of which is controlled by the parameter **tol**. In some cases the initial guess for the Newton-Raphson procedure is exact and no further iterations are required.

8 Further Comments

The function must only be used to calculate the numerical flux for the Euler equations in exactly the form given by (2), with **uleft**[$i - 1$] and **uright**[$i - 1$] containing the left and right values of ρ , m and e for $i = 1, 2, 3$ respectively.

For some problems the function may fail or be highly inefficient in comparison with an Approximate Riemann Solver (e.g., `nag_pde_parab_1d_euler_roe` (d03puc), `nag_pde_parab_1d_euler_osher` (d03pvc) or `nag_pde_parab_1d_euler_hll` (d03pwc)). Hence it is advisable to try more than one Riemann solver and to compare the performance and the results.

The time taken is independent of all input parameters other than **tol**.

9 Example

This example uses `nag_pde_parab_1d_cd_ode` (d03plc) and `nag_pde_parab_1d_euler_exact` (d03pxc) to solve the Euler equations in the domain $0 \leq x \leq 1$ for $0 < t \leq 0.035$ with initial conditions for the primitive variables $\rho(x,t)$, $u(x,t)$ and $p(x,t)$ given by

$$\begin{aligned} \rho(x,0) = 5.99924, \quad u(x,0) &= 19.5975, \quad p(x,0) = 460.894, & \text{for } x < 0.5, \\ \rho(x,0) = 5.99242, \quad u(x,0) &= -6.19633, \quad p(x,0) = 46.095, & \text{for } x > 0.5. \end{aligned}$$

This test problem is taken from Toro (1996) and its solution represents the collision of two strong shocks travelling in opposite directions, consisting of a left facing shock (travelling slowly to the right), a right travelling contact discontinuity and a right travelling shock wave. There is an exact solution to this problem (see Toro (1996)) but the calculation is lengthy and has therefore been omitted.

9.1 Program Text

```

/* nag_pde_parab_1d_euler_exact (d03pxc) Example Program.
 *
 * Copyright 2001 Numerical Algorithms Group.
 *
 * Mark 7, 2001.
 */

#include <stdio.h>
#include <nag.h>
#include <nag_stdlib.h>
#include <nagd03.h>
#include <nagx01.h>
#include <math.h>

/* Structure to communicate with user-supplied function arguments */

struct user
{
    double elo, ero, rlo, rro, ulo, uro, gamma;
};

static void bndary(Integer, Integer, double, const double[],
                  const double[], Integer, const double[],
                  const double[], Integer, double[], Integer *,
                  Nag_Comm *);

static void numflx(Integer, double, double, Integer, const double[],
                  const double[], const double[], double[], Integer *,
                  Nag_Comm *, Nag_D03_Save *);

#define U(I,J) u[npde*((J)-1)+(I)-1]
#define UE(I,J) ue[npde*((J)-1)+(I)-1]

int main(void)
{
    const Integer npde=3, npts=141, ncode=0, nxi=0, neqn=npde*npts+ncode,
        lisave=neqn+24, intpts=9, nwkres=npde*(2*npts+3*npde+32)+7*npts+4,
        lenode=9*neqn+50, mlu=3*npde-1, lrsave=(3*mlu+1)*neqn+nwkres+lenode;
    double d, p, tout, ts, v;
    Integer exit_status, i, ind, itask, itol, itrace, k;
    double *algotp=0, *atol=0, *rtol=0, *u=0,
        *ue=0, *rsave=0, *x=0, *xi=0;
    Integer *isave=0;
    NagError fail;
    Nag_Comm comm;
    Nag_D03_Save saved;
    struct user data;

    /* Allocate memory */

```

```

if ( !(algotp = NAG_ALLOC(30, double)) ||
    !(atol = NAG_ALLOC(1, double)) ||
    !(rtol = NAG_ALLOC(1, double)) ||
    !(u = NAG_ALLOC(npde*npts, double)) ||
    !(ue = NAG_ALLOC(npde*intpts, double)) ||
    !(rsave = NAG_ALLOC(lrsave, double)) ||
    !(x = NAG_ALLOC(npts, double)) ||
    !(xi = NAG_ALLOC(1, double)) ||
    !(isave = NAG_ALLOC(lisave, Integer)) )
{
    Vprintf("Allocation failure\n");
    exit_status = 1;
    goto END;
}

INIT_FAIL(fail);
exit_status = 0;

Vprintf("d03pxc Example Program Results\n");

/* Skip heading in data file */

Vscanf("%*[\n] ");

/* Problem parameters */

data.gamma = 1.4;
data.rlo = 5.99924;
data.rro = 5.99242;
data.ulo = 5.99924*19.5975;
data.uro = -5.99242*6.19633;
data.elo = 460.894/(data.gamma-1.0) + 0.5*data.rlo*19.5975*19.5975;
data.ero = 46.095/(data.gamma-1.0) + 0.5*data.rro*6.19633*6.19633;
comm.p = (Pointer)

/* Initialise mesh */

for (i = 0; i < npts; ++i) x[i] = i/(npts-1.0);

/* Initial values */

for (i = 1; i <= npts; ++i)
{
    if (x[i-1] < 0.5)
    {
        U(1, i) = data.rlo;
        U(2, i) = data.ulo;
        U(3, i) = data.elo;
    } else if (x[i-1] == 0.5) {
        U(1, i) = 0.5*(data.rlo + data.rro);
        U(2, i) = 0.5*(data.ulo + data.uro);
        U(3, i) = 0.5*(data.elo + data.ero);
    } else {
        U(1, i) = data.rro;
        U(2, i) = data.uro;
        U(3, i) = data.ero;
    }
}

itrace = 0;
itol = 1;
atol[0] = 0.005;
rtol[0] = 5e-4;
xi[0] = 0.0;
ind = 0;
itask = 1;
for (i = 0; i < 30; ++i) algopt[i] = 0.0;

/* Theta integration */

algotp[0] = 2.0;

```

```

algopt[5] = 2.0;
algopt[6] = 2.0;

/* Max. time step */

algopt[12] = 0.005;

ts = 0.0;
tout = 0.035;

d03plc(npde, &ts, tout, d03plp, numflx, bndary, u, npts, x,
       ncode, d03pek, nxi, xi, neqn, rtol, atol, itol, Nag_TwoNorm,
       Nag_LinAlgBand, algopt, rsave, lrsave, isave, lisave, itask,
       itrace, 0, &ind, &comm, &saved, &fail);

if (fail.code != NE_NOERROR)
{
  Vprintf("Error from d03plc.\n%s\n", fail.message);
  exit_status = 1;
  goto END;
}

Vprintf(" t = %6.3f\n\n", ts);
Vprintf("      x      APPROX d      EXACT d      APPROX v      EXACT v");
Vprintf("      APPROX p      EXACT p\n");

/* Read exact data at output points */

for (i = 1; i <= intpts; ++i)
{
  Vscanf("%lf", &UE(1,i));
  Vscanf("%lf", &UE(2,i));
  Vscanf("%lf", &UE(3,i));
}

/* Calculate density, velocity and pressure */

k = 0;
for (i = 15; i <= 127; i += 14)
{
  ++k;
  d = U(1, i);
  v = U(2, i)/d;
  p = d*(data.gamma-1.0)*(U(3, i)/d - 0.5*v*v);
  Vprintf(" %8.2e", x[i-1]);
  Vprintf(" %10.4e", d);
  Vprintf(" %10.4e", UE(1,k));
  Vprintf(" %10.4e", v);
  Vprintf(" %10.4e", UE(2,k));
  Vprintf(" %10.4e", p);
  Vprintf(" %10.4e\n", UE(3,k));
}

Vprintf("\n");
Vprintf(" Number of integration steps in time = %6ld\n", isave[0]);
Vprintf(" Number of function evaluations = %6ld\n", isave[1]);
Vprintf(" Number of Jacobian evaluations = %6ld\n", isave[2]);
Vprintf(" Number of iterations = %6ld\n\n", isave[4]);

END:

if (algopt) NAG_FREE(algopt);
if (atol) NAG_FREE(atol);
if (rtol) NAG_FREE(rtol);
if (u) NAG_FREE(u);
if (ue) NAG_FREE(ue);
if (rsave) NAG_FREE(rsave);
if (x) NAG_FREE(x);
if (xi) NAG_FREE(xi);
if (isave) NAG_FREE(isave);

```

```

    return exit_status;
}

static void bndary(Integer npde, Integer npts, double t, const double x[],
                  const double u[], Integer ncode, const double v[],
                  const double vdot[], Integer ibnd, double g[],
                  Integer *ires, Nag_Comm *comm)
{
    struct user *data = (struct user *)comm->p;

    if (ibnd == 0)
    {
        g[0] = U(1, 1) - data->rlo;
        g[1] = U(2, 1) - data->ulo;
        g[2] = U(3, 1) - data->elo;
    } else {
        g[0] = U(1, npts) - data->rro;
        g[1] = U(2, npts) - data->uro;
        g[2] = U(3, npts) - data->ero;
    }
    return;
}

static void numflx(Integer npde, double t, double x, Integer ncode,
                  const double v[], const double uleft[],
                  const double uright[], double flux[], Integer *ires,
                  Nag_Comm *comm, Nag_D03_Save *saved)
{
    struct user *data = (struct user *)comm->p;
    NagError fail;
    Integer niter = 0;
    double tol = 0.0;

    INIT_FAIL(fail);

    d03pxc(uleft, uright, data->gamma, tol, niter, flux, saved, &fail);

    if (fail.code != NE_NOERROR)
    {
        Vprintf("Error from d03pxc.\n%s\n", fail.message);
    }

    return;
}

```

9.2 Program Data

d03pxc Example Program Data

0.5999E+01	0.1960E+02	0.4609E+03
0.5999E+01	0.1960E+02	0.4609E+03
0.5999E+01	0.1960E+02	0.4609E+03
0.5999E+01	0.1960E+02	0.4609E+03
0.5999E+01	0.1960E+02	0.4609E+03
0.1428E+02	0.8690E+01	0.1692E+04
0.1428E+02	0.8690E+01	0.1692E+04
0.1428E+02	0.8690E+01	0.1692E+04
0.3104E+02	0.8690E+01	0.1692E+04

9.3 Program Results

d03pxc Example Program Results

t = 0.035

x	APPROX d	EXACT d	APPROX v	EXACT v	APPROX p	EXACT p
1.00e-01	5.9992e+00	5.9990e+00	1.9598e+01	1.9600e+01	4.6089e+02	4.6090e+02
2.00e-01	5.9992e+00	5.9990e+00	1.9598e+01	1.9600e+01	4.6089e+02	4.6090e+02
3.00e-01	5.9992e+00	5.9990e+00	1.9598e+01	1.9600e+01	4.6089e+02	4.6090e+02
4.00e-01	5.9992e+00	5.9990e+00	1.9598e+01	1.9600e+01	4.6089e+02	4.6090e+02
5.00e-01	5.9992e+00	5.9990e+00	1.9598e+01	1.9600e+01	4.6089e+02	4.6090e+02
6.00e-01	1.4227e+01	1.4280e+01	8.6600e+00	8.6900e+00	1.6878e+03	1.6920e+03

```
7.00e-01 1.4246e+01 1.4280e+01 8.6720e+00 8.6900e+00 1.6884e+03 1.6920e+03
8.00e-01 1.9214e+01 1.4280e+01 8.6742e+00 8.6900e+00 1.6892e+03 1.6920e+03
9.00e-01 3.0997e+01 3.1040e+01 8.6747e+00 8.6900e+00 1.6875e+03 1.6920e+03
```

```
Number of integration steps in time =    697
Number of function evaluations =    1708
Number of Jacobian evaluations =         1
Number of iterations =                 2
```
